Repeatability Measure for Broadband 4D Seismic

J. Burren (Petroleum Geo-Services) & D. Lecerf* (Petroleum Geo-Services)

SUMMARY

Future time-lapse broadband surveys should provide better reservoir monitoring resolution by extending the 4D signal bandwidth. In this paper, we will review the consequence of extending the signal bandwidth for the computation of 4D attributes, such as the repeatability measurement NRMS. The re-formulation of NRMS shows the sensitivity of the repeatability metric with regards to signal time-shift and signal bandwidth. Broadening the 4D signal bandwidth will result in an increase of the overall NRMS value for an equivalent seismic data with the same level on non-repeatable noise. To compare the quality of 4D seismic, regardless of bandwidth, we propose a new repeatability measure called CNRMS. The bandwidth Calibrated NRMS provides repeatability metric for any 4D seismic as it would be calculated with a reference signal bandwidth.

In order to extend the 4D signal bandwidth without compromising the repeatability, we propose that upgoing pressure wavefields extracted from dual-sensor streamer are used for base and monitor surveys. It ensures the best possible broadband repeatability and highest 4D resolution.

Introduction

Today the seismic industry is proposing new resolution standards for 3D imaging using seismic data with an extended bandwidth. These new broadband acquisition and processing technologies have not yet been validated for 4D surveys; to be certified as a broadband solution, they must provide excellent wavefield repeatability for all frequencies.

NRMS for 4D signal with extended bandwidth

The NRMS attribute, defined as normalized RMS of the difference between two datasets, is used routinely as a quality control measurement for time-lapse data. Several investigations have been published describing the sensitivity of the NRMS value to the acquisition geometry repeatability, for example Landro (1999), Kragh and Christie (2002) and Eiken *et al.* (2003). The final NRMS value is often used to quantify the quality of the 4D signal. In most cases, the NRMS values are used without considering the signal bandwidth of the data despite publications indicating a dependency of the NRMS value to the dominant frequency of the data (Calvert, 2005). Therefore, with the advent of 4D broadband technology, it is important to understand the performance of this repeatability metric.

Figure 1 illustrates the NRMS frequency dependency using a real broadband dataset acquired in the same area (with different azimuth). The band limited datasets (b) present lower NRMS than the broadband datasets (a).

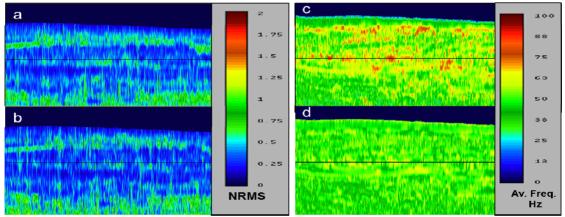


Figure 1 Repeatability metric comparison between broadband and band limited datasets: (a) NRMS for two broadband datasets; (b) NRMS for same datasets with a bandpass filter applied; (c) the average frequency for the data shown in (a), \approx 70 Hz; and (d) the data average frequency for the data shown in (b), \approx 50 Hz. Using same data, the band limited signal present lower NRMS than the broadband signal.

Equation (1) defines the NRMS metric as the normalized energy of the difference between two seismic traces (base, b and monitor, m):

$$NRMS = 2 \frac{RMS(b-m)}{RMS(b) + RMS(m)}$$
(1)

We can rewrite the expression by introducing new variables:

$$NRMS^{2} \approx 4 \frac{(1-S)^{2} SN + 1 + S^{2} + S(2\pi\tau f_{d})^{2} SN}{(1+S)^{2} (1+SN)}$$
(2)

Where: $S = Energy Ratio, RMS (m) / RMS (b); SN = Signal to Noise Ratio; <math>\tau = Time-shif, f_d = RMS freq.$ (dominant freq.)

The NRMS expression (2) is a generalization of different simplifications proposed in the literature (noted here with consistent formulation).

$$NRMS^{2} \approx SDR^{-1} + \left(2\pi \tau f_{d}\right)^{2}$$
(3) (Cantillo, 2012)

$$NRMS^{2} \approx 4 \frac{(1-S)^{2}SN + 1 + S^{2}}{(1+S)^{2}(1+SN)}$$
 (4) (Harris, 2005)

Expression (3) assumes noise free data with a RMS ratio S close to 1; SDR is defined as the trace similarity (Cantillo, 2012). Note that formulation (4) does not include any time-shift considerations.

In expressions (2), only the first term of a Taylor series has been retained, including the time-shift (τ) and the dominant frequency (f_d) implying these expressions are valid for small time-shifts. Higher order terms of the Taylor expansion would be needed to account for larger time-shifts. It should also be noted that any phase rotation and amplitude spectrum variations between base and monitor have been ignored; a matching filter should correct for such global discrepancies between the two signals. In addition, the signal to noise ratio is assumed to be similar between the base and the monitor.

The proposed formulation (2) describes the NRMS function of the Energy Ratio (S), Signal to Noise Ratio (SN), Time-shift (τ) and RMS frequency or dominant frequency (f_d). Clearly, both a variation in the time-shift and a change in the signal bandwidth significantly influence the overall NRMS value even if the differences between the two traces are very small.

Figure 2 illustrates the dependency of the NRMS with regards to the time-shift τ and the dominant frequency f_d (directly related to the signal bandwidth). The NRMS is computed for different time-shift between pairs of synthetic seismic traces having different signal bandwidth. The example assumes no phase rotation and no amplitude spectrum variation between the two traces and that both datasets have similar signal to noise.

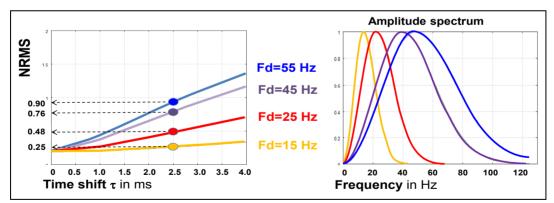


Figure 2 Graph (left) showing the change in NRMS with time-shift, τ , and dominant frequency, f_d . For a given time-shift (2.5ms) the NRMS increases with the increasing signal bandwidth. Amplitude spectra (right) for the different signals.

For a given time-shift the NRMS value will increase significantly with a change in the signal bandwidth. In other words, low frequency datasets will have lower NRMS while the presence of high frequency content will automatically lead to an increase in NRMS. Consequently, the NRMS between two sets of 4D data with different bandwidth cannot be compared directly. For the same quality of seismic, the datasets with larger bandwidth will always have a higher NRMS and appearing less repeatable.

Bandwidth Calibrated NRMS:

In order to define a repeatability metric that can be applied to data with different bandwidth, we introduce a new repeatability measure called bandwidth calibrated NRMS or *CNRMS*:

$$CNRMS^{2} = 4 \frac{(1-S)^{2} + 2S(1-\rho_{bm})(f_{dref} / f_{d})^{2}}{(1+S)^{2}}$$
(5)

Where: S = Energy ratio, RMS (m) / RMS (b); $\rho_{bm} = Correlation$ coefficient between base and monitor; $f_d = RMS$ freq. (dominant freq.); f_{dref} : reference RMS freq. (reference freq.)

In the proposed form, this measurement is valid for small timing variations between base and monitor. Figure 3 describes the same situation as in figure 2; using the new CNRMS measurement the curves are very similar for the different bandwidth examples. In this example, the NRMS has been calibrated using a reference dominant frequency of 40 Hz.

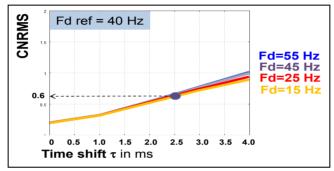


Figure 3 Graph showing the change in CNRMS with time-shift, τ , and dominant frequency, f_d . A reference frequency of 40 Hz was used to compute the CNRMS values. For a given time-shift (circles for 2.5 ms), all data now give similar and comparable CNRMS value regardless of the bandwidth.

How to increase repeatability for 4D broadband dataset?

Extending the frequency bandwidth for 4D datasets, using de-ghosting technique, will increase the sensitivity of the seismic response to reservoir changes and make the repeatability even more challenging. So, to the question; can we increase the 4D signal bandwidth without increasing the NRMS (and improving the CNRMS)? The answer should be positive if we are able to remove the non-repeatable part of the signal, especially in for the high frequencies. As it is illustrated in figure4, the ability of a dual-sensor recording system to perform accurate wavefield separation provides an opportunity to extend the signal bandwidth selecting the consistent up-going wavefield (P-UP) and discarding the down-going wavefields (ghost) affected by the sea-state variation. The benefits of using only the up-going pressure field for broadband 4D is demonstrated using a repeated sail-lines recorded with dual-sensor towed streamer. In this 4D test, the "base" and "monitor" has been acquired few months apart with the same seismic vessel for evaluating acquisition repeatability issues. Figure 4 (right) displays the repeated common shot gather for the up-going wavefield (P-UP) and for the down-going wavefield. The use of the up-going wavefield for 4D not only recovers the frequencies in the receiver ghost notches but also preserves the most repeatable part of the seismic signal. The down-going field (receiver ghost) is modified by the sea-state variations and is consequently not well suited for 4D broadband, e.g. Laws and Kragh (2002).

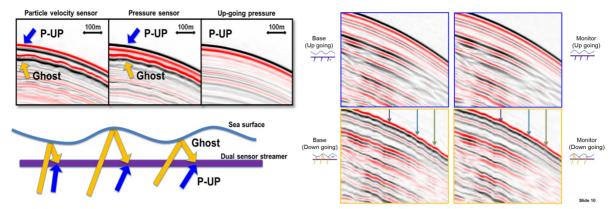


Figure 4 Zoom on a common shot gather (left) showing the recording of the vertical particle-velocity sensor, pressure sensor and the reconstructed up-going pressure wavefield. The receiver ghost undulation (yellow arrow) is due to the sea surface reflection while the up-going pressure wavefield (blue arrow) stays continuous. Repeated shot gathers (right) for the up-going wavefield (top) and for the down-going (bottom) wavefields. While the up-going is consistent the down-going (ghost) present disparate undulation related to the swell effect.

Conclusion

The formulation of the NRMS equation explains mathematically why, for constant time shift values, the NRMS computation leads to larger values if the data bandwidth is increased. A new repeatability measure, called CNRMS, introduces a normalization process for a reference dominant frequency. It provides almost identical repeatability values for a given time-shift regardless of the effective data bandwidth.

In order to extend the 4D signal bandwidth without compromising the repeatability, we propose that up-going pressure wavefields extracted from dual-sensor streamer are used for base and monitor surveys. It ensures the best possible broadband repeatability and highest 4D resolution.

Acknowledgments

Thanks to PGS for permission to publish this paper and to the imaging teams in the Rio de Janeiro office for processing the data.

References

Calvert, R. [2005] *Insights and methods for 4D reservoir monitoring and characterization*. SEG Distinguished Instructor Series, No 8, 52-53.

Cantillo J. [2012] Throwing a new light on time-lapse technology, metrics and 4D repeatability with SDR. *The Leading Edge*, **31**, 405-413.

Eiken, O., Haugen, G.U., Schonewille, M. and Duijndam, A. [2003] A proven method for acquiring highly repeatable towed streamer data. *Geophysics*, **68**, 1303-1309.

Harris, P. [2005] Prestack repeatability of time-lapse seismic data. Annual International Convention SEG, Expanded Abstracts

Kragh, E. and Christie, P. [2002] Seismic repeatability, normalised RMS, and predictability. *The Leading Edge*, **21**(7), 640-647.

Landro, M. [1999] Repeatability issues of 3-D VSP data. Geophysics, 64, 1673-1679.

Laws, R. and Kragh, E. [2002] Rough seas and time-lapse seismic. *Geophysical Prospecting*, **50**, 195-208.